

Communicative damper actuator for adjusting dampers in technical building installations

- Torque motor 5 Nm
- Nominal voltage AC/DC 24 V
- Control communicative
- Conversion of sensor signals
- Communication via KNX (S-Mode)


**Technical data**

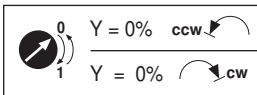
<b>Electrical data</b>	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	2.5 W
	Power consumption in rest position	1.3 W
	Power consumption for wire sizing	5 VA
	Connection supply / control	Cable 1 m, 6 x 0.75 mm <sup>2</sup>
<b>Data bus communication</b>	Medium	KNX TP
	Number of nodes	max. 64 per line segment, reduce number of nodes with connection cable with short lines
	Operating mode	S-Mode
	Current consumption of KNX-Bus	max. 5 mA
	Project planning and commissioning tool	0
<b>Functional data</b>	Torque motor	5 Nm
	Torque variable	25%, 50%, 75% reduced
	Position accuracy	±5%
	Direction of motion note	Y = 0%: At switch position 0 (ccw rotation) / 1 (cw rotation)
	Direction of motion variable	electronically reversible
	Manual override	with push-button, can be locked
	Running time motor	150 s / 90°
	Running time motor variable	35...150 s
	Adaptation setting range	manual
	Adaptation setting range variable	No action Adaptation when switched on Adaptation after pushing the gear disengagement button
	Override control, controllable via bus communication	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position) = 50%
	Override control variable	MAX = (MIN + 32%)...100% MIN = 0%...(MAX - 32%) ZS = MIN...MAX
	Sound power level, motor	35 dB(A)
	Position indication	Mechanically, pluggable
	<b>Safety</b>	Protection class IEC/EN
Degree of protection IEC/EN		IP54
EMC		CE according to 2014/30/EU
Certification IEC/EN		IEC/EN 60730-1 and IEC/EN 60730-2-14
Mode of operation		Type 1
Rated impulse voltage supply / control		0.8 kV
Control pollution degree		3
Ambient temperature		-30...50 °C
Storage temperature		-40...80 °C
Ambient humidity		Max. 95% r.H., non-condensing
Servicing	maintenance-free	
<b>Weight</b>	Weight	0.65 kg

## Safety notes



- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

## Product features

<b>Mode of operation</b>	The actuator is equipped with an integrated interface for KNX (S-Mode) and can be connected with all KNX devices that have corresponding data points available.
<b>Converter for sensors</b>	Connection option for a sensor (passive or active sensor or switching contact). In this way, the analogue sensor signal can be easily digitised and passed along to KNX.
<b>Parametrisable actuators</b>	The factory settings cover the most common applications. As desired, individual parameters can be adapted for specific systems or servicing with a service tool (e.g. ZTH EU) or the ETS planning and commissioning tool.
<b>Simple direct mounting</b>	Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating.
<b>Manual override</b>	Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).
<b>Adjustable angle of rotation</b>	Adjustable angle of rotation with mechanical end stops.
<b>High functional reliability</b>	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
<b>Home position</b>	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal.
<b>Adaption and synchronisation</b>	<div style="border: 1px solid black; padding: 5px; width: fit-content; margin-bottom: 10px;">  </div> <p>An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range). Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal. A range of settings can be adapted using the PC-Tool (see MFT-P documentation)</p>

## Accessories

	Description	Type
<b>Electrical accessories</b>	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin service socket for Belimo device	ZK1-GEN
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
	Auxiliary switch 1 x SPDT add-on	S1A
	Auxiliary switch 2 x SPDT add-on	S2A
	Auxiliary switch 2 x SPDT add-on, grau	S2A/300 GR
	Auxiliary switch 2 x SPDT add-on, grau	S2A/500 GR
	Feedback potentiometer 140 Ω add-on	P140A
	Feedback potentiometer 140 Ω add-on, grau	P140A GR
	Feedback potentiometer 200 Ω add-on	P200A
	Feedback potentiometer 500 Ω add-on	P500A
	Feedback potentiometer 500 Ω add-on, grau	P500A GR
	Feedback potentiometer 1 kΩ add-on	P1000A
	Feedback potentiometer 1 kΩ add-on, grau	P1000A GR
	Feedback potentiometer 2.8 kΩ add-on	P2800A
	Feedback potentiometer 2.8 kΩ add-on, grau	P2800A GR
	Feedback potentiometer 5 kΩ add-on	P5000A
	Feedback potentiometer 5 kΩ add-on, grau	P5000A GR
Feedback potentiometer 10 kΩ add-on	P10000A	
Feedback potentiometer 10 kΩ add-on, grau	P10000A GR	
<b>Mechanical accessories</b>	<b>Description</b>	<b>Type</b>
	Shaft extension 170 mm Ø10 mm for damper shaft Ø 6...16 mm	AV6-20
	Shaft clamp one-sided, clamping range Ø6...20 mm, Multipack 20 pcs.	K-ELA
	Shaft clamp one-sided, clamping range Ø6...10 mm, Multipack 20 pcs.	K-ELA10
	Shaft clamp one-sided, clamping range Ø6...13 mm, Multipack 20 pcs.	K-ELA13
	Shaft clamp one-sided, clamping range Ø6...16 mm, Multipack 20 pcs.	K-ELA16
	Anti-rotation mechanism 180 mm, Multipack 20 pcs.	Z-ARS180
	Form fit insert 8x8 mm, Multipack 20 pcs.	ZF8-LMA
	Form fit insert 10x10 mm, Multipack 20 pcs.	ZF10-LMA
	Form fit insert 12x12 mm, Multipack 20 pcs.	ZF12-LMA
	Form fit insert 8x8 mm, with angle of rotation limiter and position indication, Multipack 20 pcs.	ZFRL8-LMA
	Form fit insert 10x10 mm, with angle of rotation limiter and position indication, Multipack 20 pcs.	ZFRL10-LMA
	Form fit insert 12x12 mm, with angle of rotation limiter and position indication, Multipack 20 pcs.	ZFRL12-LMA
	Position indicator, Multipack 20 pcs.	Z-PI
<b>Service Tools</b>	<b>Description</b>	<b>Type</b>
	Service Tool, with ZIP-USB function	ZTH EU
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
Adapter for Service-Tool ZTH	MFT-C	

## Electrical installation

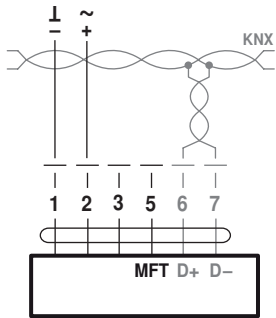
**Notes**

- Connection via safety isolating transformer.

Electrical installation

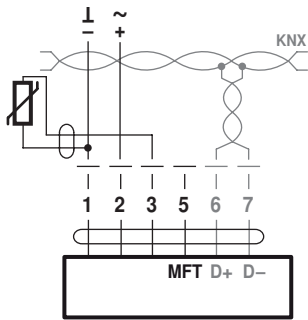
Wiring diagrams

Connection without sensor



Signal assignment KNX:  
 D+ = KNX+ (pink > red)  
 D- = KNX- (grey > black)  
 The connection to the KNX line should take place via WAGO connecting terminals 222/221.

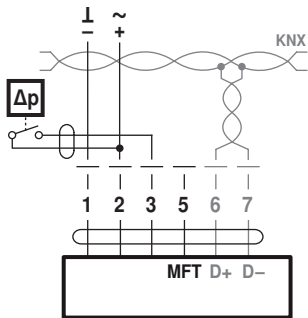
Connection with passive sensor, e.g. Pt1000, Ni1000, NTC



Ni1000	-28...+98 °C	850...1600 Ω <sup>2)</sup>
PT1000	-35...+155 °C	850...1600 Ω <sup>2)</sup>
NTC	-10...+160 °C <sup>1)</sup>	200 Ω...60 kΩ <sup>2)</sup>

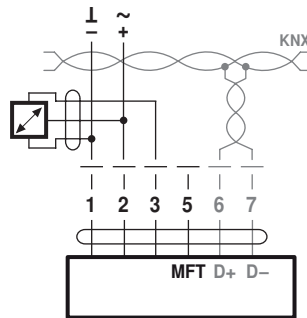
- 1) depending on type
- 2) Resolution 1 Ohm

Connection with switching contact, e.g. pressure control device



Requirements switching contact:  
 The switching contact must be able to accurately switch a current of 16 mA@24 V.

Connection with active sensor, e.g. 0...10 V @ 0...50 °C



Possible voltage range:  
 0...32 V (resolution 30 mV)

## KNX group objects

Name	Type	Flags					Data point type				Values range
		C	R	W	T	U	ID	DPT_Name	Format	Unit	
Setpoint	I	C	-	W	-	-	5.001	_Scaling	1 Byte	%	[0...100] Resolution 0.4%
Override control	I	C	-	W	-	-	20.*	_Enum	1 Byte	-	0 = no override 1 = Open 2 = Closed 3 = Min 4 = Mid 5 = Max
Reset	I	C	-	W	-	-	1.015	_Reset	1 Bit	-	0 = no action 1 = reset
Adaptation	I	C	-	W	-	-	1.017	_Switch	1 Bit	-	0 = no action 1 = adapt
Testrun	I	C	-	W	-	-	1.017	_Switch	1 Bit	-	0 = no action 1 = Testrun
Min	I/O	C	R	W	-	-	5.001	_Scaling	1 Byte	%	[0...100] Resolution 0.4%
Max	I/O	C	R	W	-	-	5.001	_Scaling	1 Byte	%	[0...100] Resolution 0.4%
Relative position	O	C	R	-	T	-	5.001	_Scaling	1 Byte	%	[0...100] Resolution 0.4%
Absolute position	O	C	R	-	T	-	8.011 7.011	_Rotation_Angle _Length_mm	2 Byte	° mm	[-32,768...32,768] [0...65,535]
Fault state	O	C	R	-	T	-	1.002	_Bool	1 Bit	-	0 = no fault 1 = fault
Overridden	O	C	R	-	T	-	1.002	_Bool	1 Bit	-	0 = not active 1 = active
Gear disengaged	O	C	R	-	T	-	1.002	_Bool	1 Bit	-	0 = engaged 1 = disengaged
Service information	O	C	R	-	T	-	22.*	_Bitset16	2 Byte	-	Bit 0 (1) Excessive utilisation Bit 1 (2) Mechanical travel increased Bit 2 (4) Mechanical overload Bit 3 (8) – (Not used) Bit 4 (16) – (Not used) Bit 5 (32) – (Not used) Bit 6 (64) – (Not used) Bit 7 (128) – (Not used) Bit 8 (256) Internal activity Bit 9 (512) Bus watchdog triggered
Sensor value	O	C	R	-	T	-					
– Resistance R							14.060	_Value_Resistance	4 Byte	Ω	–
– Temperature							9.001	_Value_Temp	2 Byte	°C	[-273.....670'760]
– Relative humidity							9.007	_Value_Humidity	2 Byte	% rH	[0...670'760]
– Air quality							9.008	_Value_AirQuality	2 Byte	ppm	[0...670'760]
– Voltage mV							9.020	_Value_Voltage	2 Byte	mV	[-670'760...670'760]
– Voltage scaled							7.*	–	2 Byte	–	[0...65'535]
– Voltage scaled %							5.001	_Scaling	1 Byte	%	[0...100]
– Switch							1.001	_Switch	–	–	0/1

## KNX group objects

<b>Setpoint</b>	Specification of actuator position in % between the parameterised Min and Max limits.
<b>Override control</b>	Overriding the setpoint with defined override states. As data point type, 1 Byte (unsigned) is recommended (DPT 20.*)
<b>Reset</b>	Resetting the stored service messages (see KNX group object <i>Service information</i> ).
<b>Adaptation</b>	Perform the adaptation. An active adaptation is signaled in Bit 8 of <i>Service information</i> .
<b>Testrun</b>	Performance of a testrun that checks the entire operating range. An active testrun is signaled in Bit 8 of <i>Service information</i> . After completion, detected faults (mechanical overload, mechanical travel increased) are signaled in <i>Service Information</i> .
<b>Min</b>	Minimum Limit (position) in %. Caution: Changing the setting may result in malfunctions.
<b>Max</b>	Maximum Limit (position) in %. Caution: Changing the setting may result in malfunctions.
<b>Relative position</b>	Current actuator position in %
<b>Absolute position</b>	Absolute position/stroke The data point type is to be selected depending on the type of movement: [°] DPT 8.011 [mm] DPT 7.011
<b>Fault state</b>	Collective fault based on Bit 0 ... Bit 7 of <i>Service information</i>
<b>Overridden</b>	Signaling of an active override control (OPEN/CLOSED) The device can be commanded via the KNX group object <i>Override control</i> or via the forced switching at the input Y/3. Only the override controls OPEN and CLOSED are signaled.
<b>Gear disengaged</b>	Signaling an active gear disengagement
<b>Service information</b>	Detailed information regarding device status As data point type, Bitset 16-Bit is recommended (DPT 22.*) Status information Bit 0: Motor operation in relation to operating period too high Bit 1: Mechanical travel increased, e.g. defined end position exceeded Bit 2: Mechanical overload, i.e. defined end position not reached Bit 3 ... 7: not used with this device type Bit 8: Internal activity (Synchronisation, Adaptation, Testrun, ...) Bit 9: Bus watchdog triggered Bit 0 ... Bit 7 are stored by the device and can be reset with the KNX group object <i>Reset</i> . As an alternative, the several bits can be read as collective fault state.
<b>Sensor value</b>	The representation of the sensor value is dependent on the parameterization. See section "KNX parameters – Sensor"

## KNX parameters

## Common

- Setpoint at bus failure** A setpoint can be defined for cases of communication interruption.  
 Values range: None (last setpoint)  
 Open  
 Closed  
 Mid  
 Factory setting: None (last setpoint)  
 The monitoring of the communication takes place for the KNX group objects *Setpoint* and *Override control*. If none of the objects is written within the parameterised monitoring time, the bus fail position is set and signaled in the *Service information* (Bit 9).
- Bus timeout [min]** Monitoring time for the detection of a communication interruption.  
 Values range: 1 ... 120 min  
 Factory setting: –
- Increment for value update [%]** Actual values (position, volumetric flow) are transferred at the time of a value change insofar as these change by the parameterised difference value. If the relative value changes by the difference value, not only the relative actual value but also the absolute actual value are transferred.  
 Values range: 0 ... 100%  
 Factory setting: 5%  
 The transfer is deactivated with 0% in the event of a value change.
- Repetition time [s]** Repetition time for all position and sensor actual values. Status objects are not transferred except with a change.  
 Values range: 0 ... 3600 s  
 Factory setting: 0 = no periodic transmission

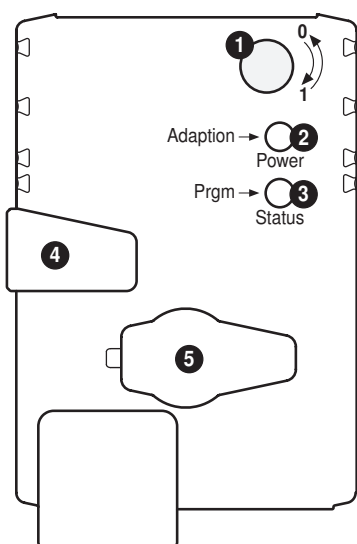
## Sensor

- Sensor type** The input Y/3 can be used to connect a sensor. The sensor value is digitised and made available as KNX communication object.  
 Values range: No sensor  
 Active sensor (0 ... 32 V)  
 Passive sensor 1 K  
 Passive sensor 20 K  
 Switch (0 / 1)  
 Temperature sensor PT1000 / Ni1000 / NTG10K  
 Humidity sensor (0 ... 10 V corresponds to 0 ... 100%)  
 Air quality sensor CO2 (0 ... 10 V corresponds to 0 ... 2000 ppm)  
 Factory setting: No sensor  
 A switching to Y/3 is treated as local override in the absence of sensor parameterization.
- Increment for sensor value update** The sensor value is transferred at the time of a value change insofar as this changes by the parameterised difference value.  
 Values range: 0 ... 65,535  
 Factory setting: 1  
 The transfer is deactivated with 0 in the event of a value change. Without value change, the sensor value is sent because of the repetition time.
- Output** Only for "Active sensor" sensor type  
 (for sensor type "Active sensor") Values range: Sensor value mV (DPT 9.020)  
 Sensor value scaled (DPT 7.xxx)  
 Sensor value scaled % (DPT 5.001)  
 Factory setting: –  
 For "Sensor value mV", the measured voltage is made available without processing. In the case of the scaled sensor values, a linear transformation can be defined with two points.
- Polarity** The polarity can be defined for the sensor type "Switch".  
 (for sensor type "Switch") Values range: Normal  
 Inverted  
 Factory setting: –

## KNX workflows

- Product database** The product database for the import in ETS4 or higher is available at the Belimo website [www.belimo.eu](http://www.belimo.eu) (Download Center)
- Setting physical address** The programming of the physical address takes place by ETS and the programming button on the device.
- If the programming button is not accessible or accessible only with difficulty, then the address can be set using a point-to-point connection: "Overwrite Individual Address: 15.15.255"
- As a third possibility, the physical address can be programmed on the basis of the KNX series number (e.g. with Moov'n'Group). The KNX series number is placed on the device in two versions. One sticker can be removed for adhesion on the commissioning journal, for example.
- Firmware upgrade** The KNX firmware of the device is updated automatically with the programming of the application program insofar as the product database has a more recent version.
- The first programming procedure takes somewhat longer in such cases (>1 min).
- Resetting to KNX factory settings** If necessary, the device can be reset manually to the KNX factory settings (physical address, group address, KNX parameters).
- For the reset, the programming button on the device must be pressed down for at least 5 s during start-up.

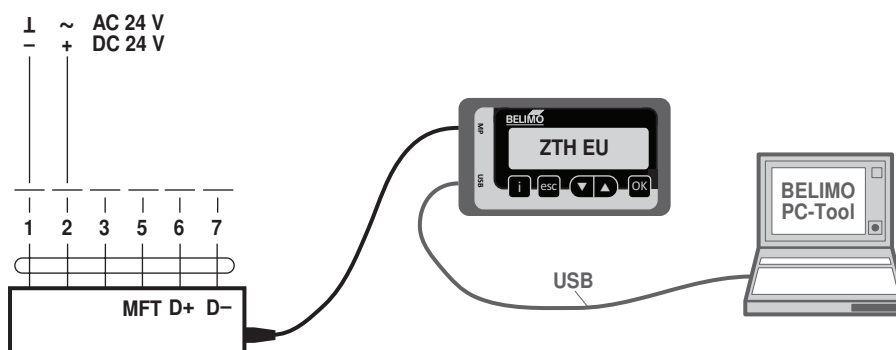
## Operating controls and indicators



- 1 Direction of rotation switch**  
Switch over: Direction of rotation changes
- 2 Push-button and LED display green**  
Off: No power supply or malfunction  
On: In operation  
Press button: Triggers angle of rotation adaptation, followed by standard mode
- 3 Push-button and LED display yellow**  
Off: The actuator is ready  
On: Adaptation or synchronising process active or actuator in programming mode (KNX)  
Flashing: Connection test (KNX) active  
Press button: In operation (>3 s): Switch the programming mode on and off (KNX)  
When starting (>5 s): Reset to factory setting (KNX)
- 4 Gear disengagement button**  
Press button: Gear disengages, motor stops, manual override possible  
Release button: Gear engages, synchronisation starts, followed by standard mode
- 5 Service plug**  
For connecting parameterisation and service tools

## Service

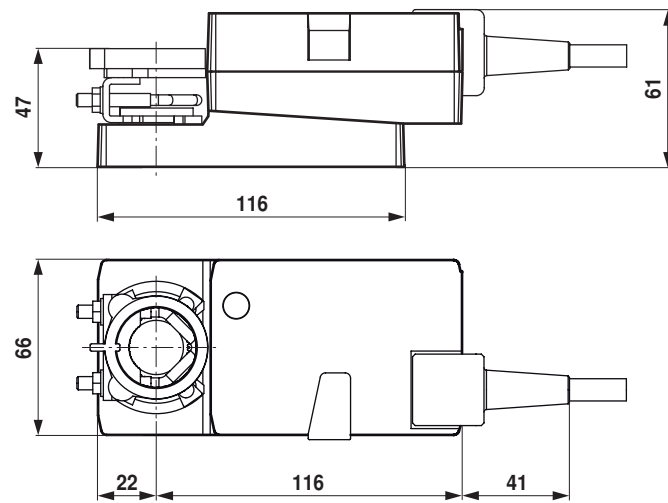
- Service Tools connection** The actuator can be parametrised by ZTH EU via the service socket. For an extended parameterisation the PC tool can be connected.





## Dimensions [mm]

## Dimensional drawings



## Further documentation

- Tool connections
- General notes for project planning